

GSK: Universally Accessible Graph SKetching

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ABSTRACT

Combinatorial graphs, often conveyed as node-link diagrams, figure prominently in Computer Science and other Science, Technology, Engineering, and Mathematics (STEM) disciplines. Unfortunately, they are most often inaccessible to blind students and professionals. This paper introduces GSK, a self-contained Graph SKetching tool, that allows blind and sighted people to easily create, edit, and share graphs in real-time using interaction mechanisms (mouse, keyboard, monitor, screen reader) that are standard for them. GSK was successfully used by a blind Computer Science student and his sighted instructors to create and access graphs specific to his automata theory and operating systems courses. Our hope is that GSK will enable more blind STEM students and professionals to actively participate in their disciplines by providing them and their sighted colleagues with a cross-collaboration tool that allows them to share graphs just as easily as they share text and word processing documents.

Categories and Subject Descriptors

D.4.1 [Operating Systems]: Process Management – *deadlocks*;
F.1.1 [Computation by Abstract Devices]: Models of Computation – *automata*; F.1.3 [Computation by Abstract Devices]: Complexity Measures and Classes – *reducibility and completeness*; G.2.2 [Discrete Mathematics]: Graph Theory;
H.5.2 [Information Interfaces and Presentation]: User Interfaces;
K.3.2 [Computers and Education]: Computer and Information Science Education;
K.4.2 [Computers and Society]: Social Issues – *assistive technologies for persons with disabilities*.

General Terms

Human Factors.

Keywords

Universal Design, Accessibility, Computational Equivalence.

1. INTRODUCTION

We developed GSK, a self-contained Graph SKetching tool, to provide a universally accessible means of creating, editing, and sharing combinatorial graphs, also known as node-link diagrams. A combinatorial graph consists of nodes joined by edges. While a

very simple structure, it figures prominently in Computer Science and other Science, Technology, Engineering, and Mathematics (STEM) disciplines.¹ Entity relationship diagrams, finite-state machines, various Universal Modeling Language (UML) diagrams, resource-allocation graphs, chemical molecules, etc., are all represented using (combinatorial) graphs. Unfortunately, these representations are generally not accessible to blind students and professionals forming a barrier between them and active participation in STEM fields. Our goal is to help remove that barrier by providing blind people with the means to independently create and use graphs in a variety of disciplines for knowledge representation and problem solving, and to easily share them with sighted people.

2. DESIGN CONSIDERATIONS

The principles of *universal design* and *computational equivalence* as well as a desire to *level the playing field* for blind people guided our design of GSK.

2.1 Universal Design

Universal design principles espouse the development of products that are equitable in use without segregating users [3]. A number of applications have been developed *separately* and *specifically* to provide blind users with access to various types of graphs [1, 2, 4, 6, 7, 9]. However, separate is most often not equal and it is important that blind users be included in software applications intended for universal use. Work is now underway to include blind students in the use of JFLAP, a popular automata theory platform [5]. Our prior experience with making our graph-based automata theory application, ProofChecker, accessible to blind students without affecting the sighted interface [10] inspired us to do the same for generalized graph editing.

Text editors and word processing programs are useable by both sighted and blind people via interaction mechanisms that are standard for them (mouse, keyboard, monitor, screen reader). When a blind and a sighted person are working together on a text or word processing document, they have immediate access to changes made by the other. GSK is designed to provide the same type of experience for graph editing for both blind and sighted people in terms of ease of use and document sharing.

2.2 Computational Equivalence

In order to use graphs for problem solving, it is important that blind people have graph representations that are *computationally equivalent* and not simply *informationally equivalent* to those

¹ A recent issue of the Communications of the ACM (June 2011) contained over 20 graphs representing networks, structural equation analysis, page ranking, record assembly, and verification pipelines, among other things, within its 128 pages.

available to sighted people. Larkin and Simon distinguish between informational and computational equivalence as follows:

Two representations are informationally equivalent if all of the information in the one is also inferable from the other, and vice versa. Each could be constructed from the information in the other. Two representations are computationally equivalent if they are informationally equivalent and, in addition, any inference that can be drawn easily and quickly from the information given explicitly in the one can be drawn easily and quickly from the information given explicitly in the other, and vice versa. [8]

Oftentimes graphs are provided to blind people in the form of tables which are informationally equivalent but not generally computationally equivalent to the node-link diagrams typically used by sighted people. As one blind student studying finite-state machines (FSMs) succinctly put it, he was “stuck in table mode” while his sighted peers had the advantage of easily moving from state to state of an FSM by following the edges (transitions) of a node-link diagram representation.

To further illustrate this point, consider the following example from automata theory. A deterministic finite automaton (DFA) is a form of directed graph that is used to determine whether or not a string (sequence of characters) is a member of a regular language. A DFA is said to “accept” or “reject” a string in terms of membership in its language. Table 1 and Figure 1 below provide *informationally equivalent* representations of the same DFA, i.e., each could be created from the information provided in the other.

Table 1. Transition table representation of a DFA

δ	a	b
q_0	q_2	q_3
* q_1	q_0	q_1
q_2	q_0	q_1
q_3	q_2	q_3

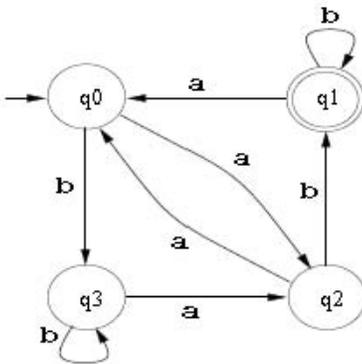


Figure 1. Node-link diagram representation of a DFA

In this example, the alphabet $\Sigma = \{a, b\}$ and the set of states $Q = \{q_0, q_1, q_2, q_3\}$. The first state in the transition table, q_0 , is the start state and is designated as such by an incoming arrow in the node-link diagram. The accepting state, q_1 is preceded by an asterisk (*) in the table and denoted by a double circle in the diagram. This

DFA may be used to tell whether or not a string consisting of 0 or more a’s and b’s has an odd number of a’s and ends with b.

For example, to determine whether the string *abbabab* is accepted by the DFA above involves moving from state to state while reading the current input symbol as illustrated by the following sequence of configurations:

$(q_0, \text{abbabab}) \vdash (q_2, \text{bbabab}) \vdash (q_1, \text{babab}) \vdash (q_1, \text{abab}) \vdash$

$(q_0, \text{bab}) \vdash (q_3, \text{ab}) \vdash (q_2, \text{b}) \vdash (q_1, \epsilon)$

Because q_1 , the last state reached in the computation, is an accepting state, the string is indeed in the language of the DFA.

Imagine a sighted person carrying out the above computation by moving a finger back and forth and up and down the rows of the transition table which is analogous to the way a blind person would access an electronic form of the table. Using a table representation, the time to determine the inclusion of a string w in the language of a DFA is proportional to the number of states times the size of its alphabet times the length of the string, or borrowing from complexity theory, $\Theta(|Q| |\Sigma| |w|)$. On the other hand a sighted person moving a finger from state to state of a node-link diagram following the transition corresponding to the current input symbol could complete the computation in time proportional to the size of the alphabet times the length of the string, or $\Theta(|\Sigma| |w|)$. For a DFA with a large number of states, the time savings would be considerable. Thus, the two representations are *not computationally equivalent*.

Our design of GSK aims to relieve blind students and professionals of the disadvantage of being stuck in table mode and instead provides them with the computational advantage of being able to easily traverse the edges of a graph and otherwise efficiently create, edit, and access graphs.

2.3 Leveling the Playing Field

Besides providing blind people with computationally equivalent graph representations, we would like to help enable them to function as independently and efficiently as possible in academic and professional settings. All of the graphs shown in Figures 2, 7, 8, and 10 were drawn independently by a blind student, who is also the second author of this paper. Using GSK, he was able to communicate graphs with his automata theory instructors, create and include graphs in documents for homework assignments, and quickly render the graphs necessary to solve problems on an operating system quiz. Our hope is that GSK will help to level the playing field for more blind students and professionals allowing them to fully participate in their disciplines alongside their sighted peers.

3. OVERVIEW OF GSK

GSK is a Java application built using standard Swing components that leverages the Java Accessibility API. It was developed and tested on a Windows platform using the JAWS screen reader, which requires the installation of the Java Access Bridge. The bridge provides a communication mechanism between the screen reader and the Java Virtual Machine (JVM). Being written in Java, our hope is that GSK would port well to other systems and use by other screen readers.

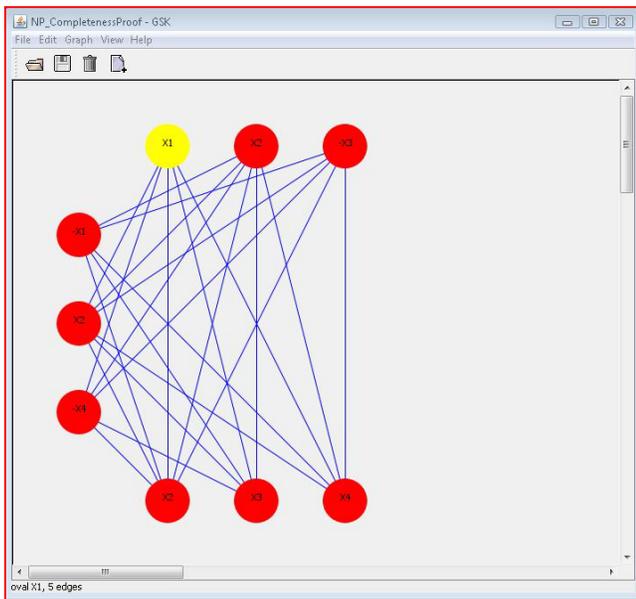


Figure 2. Connection View of an NP-Completeness Graph

GSK was developed as a collaboration between the sighted first author and the aforementioned blind second author, which was itself an exercise in universal accessibility. We found that the Eclipse platform using SVN for version control worked well for both of us. The ability provided by Eclipse to specify the indentation level of our source code and correct the indentation when necessary was particularly helpful. We used Microsoft Word to prepare our initial design documents and a raised print drawing kit whenever we needed to share a drawing of the interface, control flow, etc. Eventually, we were able to use GSK instead of the drawing kit to create and share simple flowcharts that we used in the design of subsequent functionality.

3.1 Universal Accessibility Features

GSK is intended to appeal to both sighted and blind users. In addition to providing a point-and-click interface, GSK is fully *keyboard accessible* which is crucial for blind users and in fact required by Sec. 508 accessibility guidelines. This helps make GSK useable by a wide group of users including those with mobility or other impairments.

Providing *programmatic focus* and an effective *navigation scheme* is also crucial for blind users. While sighted users can easily rest their gaze on any item on the screen, blind users must use the keyboard to navigate from item to item. When using GSK to examine a graph, the node or edge with focus is designated as the current or selected node/edge. Whenever focus is changed to a different node or edge, its name is announced by the screen reader in use by the blind user. The currently selected node or edge is also highlighted thus providing a visual focus indicator, especially important for sighted users navigating via the keyboard.

In order for blind users to create and share graphs with sighted people, they must be able to position the nodes in such a way that they are visually viewable. GSK facilitates this by providing blind users (and other users) with the means to specify the *spatial layout* of a graph.

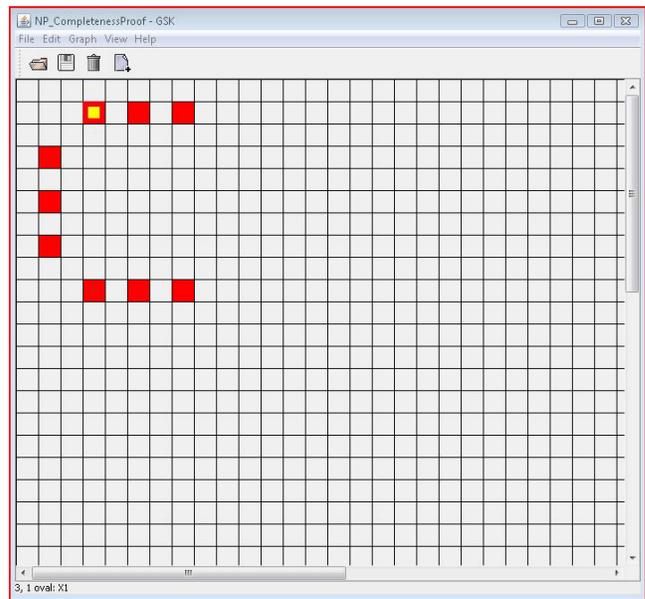


Figure 3. Grid View of Graph in Figure 2

3.2 The GSK Interface

The GSK interface shown in Figures 2 and 3 above provides two different views of the same graph, *Connection View* and *Grid View*. The user may easily switch between the two views depending on which is more appropriate for the task at hand. In addition to the large central panel where the graph is displayed, the interface contains a menu bar with File, Edit, Graph, View, and Help menus as well as a tool bar with Open, Save, Remove, and Add Edge buttons. A status bar at the bottom provides information about the currently selected node/edge or, in the absence of a graph, the name of the view. When a screen reader is in use, the status is announced whenever it changes thus allowing a blind user to track focus changes. Appropriate mnemonics and keyboard shortcuts are also provided thus allowing for multiple means of accessing each function of the interface. Graphs may be saved in .gsk format and/or exported as PNG images.

The benefits of Connection View and Grid View as well as their use in creating, editing, and navigating graphs is described below. Switching between the views is accomplished via the View Menu.

3.2.1 Connection View

Connection View provides the typical point-and-click interface and node-link diagram representation of a graph to which sighted users are accustomed. It is also useful for blind users in that it allows them to navigate a graph via the keyboard. When working together, changes to a graph that are immediately visible to a sighted user are announced to a blind user via the screen reader.

3.2.1.1 Creating, Editing, and Removing Nodes

In Connection View, a new node is created by double-clicking on an empty space on the graph panel. The Node Properties dialog box shown in Figure 4 is then displayed with default values for the node name, X and Y Locations in Grid View, shape, height, width, and color, any of which may be changed, if desired. Currently available node shapes include general *oval* and *rectangle* shapes as well as shapes pertaining to automata theory – *accepting state*, *accepting/start state*, *start state*, and *state*. We plan to add shapes for other domains such as flow charts, UML

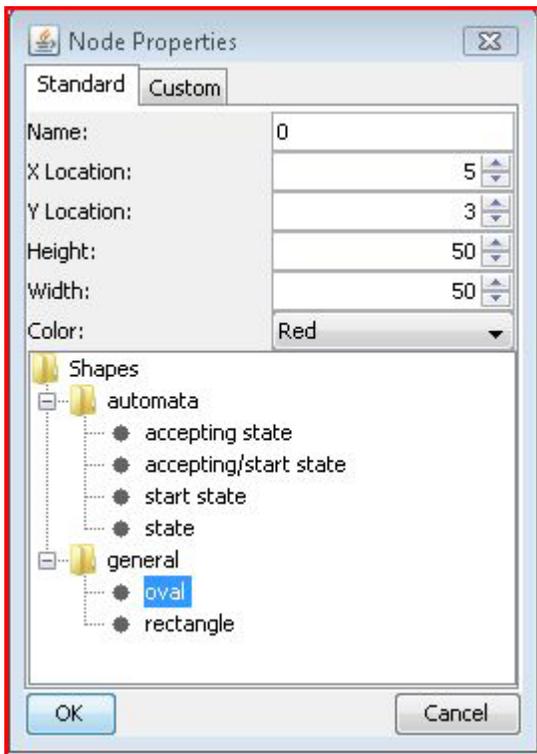


Figure 4. Node Properties Dialog Box

diagrams, etc. and have designed GSK to make this extension relatively straightforward.

The properties of an existing node may be edited by double-clicking on the node or by selecting the node and pressing Enter, both of which bring up the Node Properties dialog box. A node may be moved by changing its X and/or Y position or by dragging it to a different position. A node may be removed by selecting it and pressing the Delete key, selecting Remove from the Graph menu, or pushing the Remove button on the toolbar. Whenever a node is removed, its edges are removed as well.

3.2.1.2 Adding, Editing, and Removing Edges

An edge may be added to the selected node by pushing the Add Edge button on the toolbar, selecting Add Edge... from the Graph menu, or entering CTRL+E. The Edge Properties dialog box shown in Figure 5 is then displayed with default values for the edge name, endpoints, color, and direction. The direction choices are NONE, BIDIRECTIONAL, ENDPOINT1_TO_ENDPOINT2, and ENDPOINT2_TO_ENDPOINT1.

The properties of an existing edge may be edited by double-clicking on the edge or by selecting the edge and pressing Enter, both of which bring up the Edge Properties dialog box. An edge may be removed by selecting it and pressing the Delete key, selecting Remove from the Graph menu, or pushing the Remove button on the toolbar.

3.2.1.3 Graph Navigation

A node may be selected by clicking on it, selecting Jump to Node... from the Graph menu, or by entering CTRL+J. The latter two options bring up the Jump to Node dialog shown in Figure 6 which allows the user to choose a node from a list. The left/right arrow keys are used to move between and select the edge(s) of the

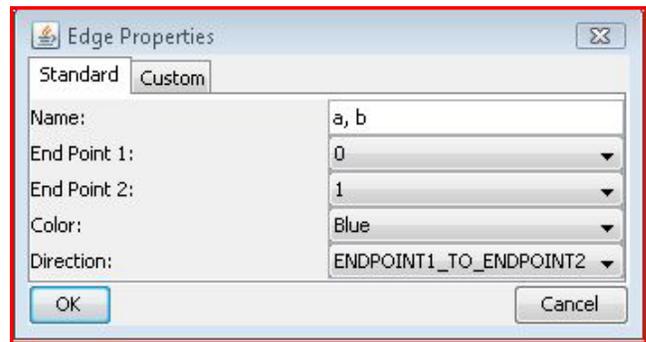


Figure 5. Edge Properties Dialog Box

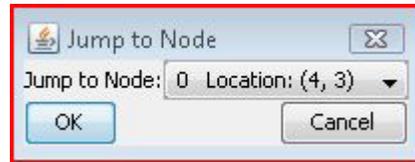


Figure 6. Jump to Node Dialog Box

node. Pressing up arrow when an edge is selected, moves focus to (selects) the opposite endpoint. Each time focus changes to a node or edge, information about the selected node/edge is displayed in the status bar and announced by the screen reader, if one is in use.

3.2.2 Grid View

Grid View provides the means to spatially lay out a graph. In this view the graph panel is divided into a grid of squares, each one of which corresponds to a potential or actual node position in Connection View. The squares are referenced by their X, Y Location in the grid with the X values starting at 0 and running horizontally across the grid and the Y values starting at 0 and running vertically down the grid. The grid squares are much smaller than the default size of nodes in Connection View and are intended to show the location of nodes relative to each other. Figures 2 and 3 provide a side by side comparison of the same graph displayed in both views.

A grid square may be selected by clicking on it or navigating to it with the up/down/left/right arrow keys. If the square contains a node, it may also be selected using the Jump to Node... action. The X, Y Location for the selected square is displayed in the status bar. If the square contains a node, the node shape and name is displayed as well. For example, in a graph used for automata theory, information about a start state named q0 with 6, 5 as its X, Y Location would be displayed as “6, 5 start state: q0.” Whenever focus changes to a new square, its status bar information is announced by the screen reader, if one is in use.

3.2.2.1 Creating, Editing, and Removing Nodes

In Grid View, a new node is created by double-clicking on an empty square or by pressing Enter when focus is on an empty square. This brings up the Node Properties dialog box as previously described which allows for changing the default values of the node, such as name, X and Y Locations, shape, and color.

The properties of an existing node may be edited by double-clicking on the square containing the node or by pressing Enter when focus is on the node’s square, both of which bring up the Node Properties dialog box. A node may be moved by changing

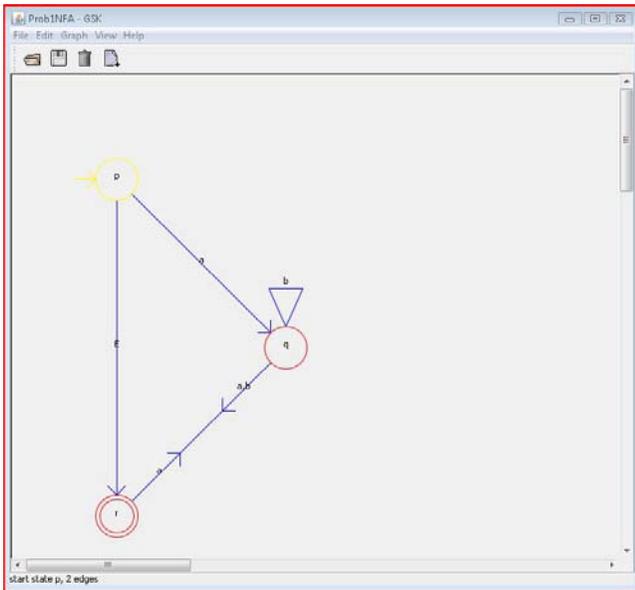


Figure 7. Nondeterministic Finite Automaton (NFA)

its X and/or Y Location via the Node Properties dialog or by cutting and pasting it in a different square using the standard CTRL+X, CTRL+V sequence. A node may be removed by selecting the square containing the node and pressing the Delete key, selecting Remove from the Graph menu, or pushing the Remove button on the toolbar. Whenever a node is removed, all of its edges are removed as well.

3.2.2.2 Adding, Editing, and Removing Edges

When in Grid View, an edge may be added to the selected node in the same way as previously described in Section 3.2.1.2. However, editing and removing existing edges requires the use of Connection View.

4. GSK IN PRACTICE

The second author, who is a blind third year Computer Science undergraduate student, successfully used GSK for assignments, tests, and quizzes in his Fall 2011 Automata Theory and Operating Systems courses. In addition to making it possible for him to create graphs to include in his course work, GSK provided him with an important problem-solving tool. It also functioned as a means for cross communication between him and the teaching staff in terms of sharing graphs. The student's use of GSK in both courses is described below.

4.1 Automata Theory Course

Graphs were used extensively throughout the Automata Theory course during the Graph Theory review, as part of NP-completeness proofs, and to represent automata – Deterministic and Nondeterministic Finite Automata (DFAs / NFAs), Pushdown Automata (PDAs), and Turing Machines. Examples of the use of GSK by the teaching staff and the second author for each of these topics are provided below.

4.1.1 Graph Theory

GSK was used by the teaching staff to render undirected graphs in the lecture notes, quizzes, and homework assignments and

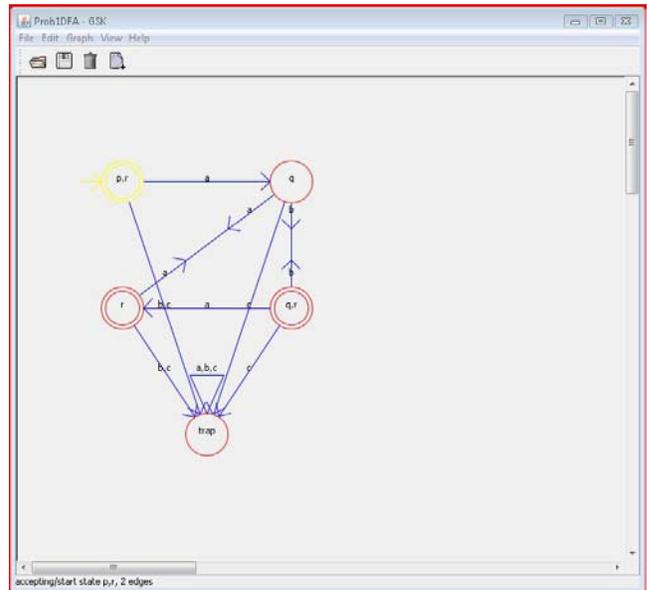


Figure 8. Deterministic Finite Automaton (DFA)

communicate them to the student. He found Connection View particularly helpful when examining the graphs to answer quiz and homework questions about Eulerian and Hamiltonian paths, cliques, independent sets, etc. He felt that these tasks would have been much more difficult had he been restricted to examining the graphs in table form.

4.1.2 NP-Completeness Proofs

As part of an NP-Completeness proof, the student was required to create a graph representation of the Boolean expression $(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee x_3 \vee x_4)$. He used GSK to create this graph as shown in Figure 2, which he then exported as a PNG image and included in his LaTeX homework document. Using Grid View as shown in Figure 3 to layout the graph was very helpful.

4.1.3 Automata

Besides using GSK to render the various types of automata, the student used it to convert an NFA to an equivalent DFA as shown in Figures 7 and 8. To determine whether a DFA was equivalent to a given regular expression, he generated strings using the regular expression and then used Connection View to check if the strings were accepted by the DFA. Again, he felt that using GSK was much more efficient than having to rely on transition table representations of the automata and that it provided him with computationally equivalent graph representations to those available to sighted students.

4.2 Operating Systems Course

The Operating Systems course only made use of one type of graph – a system resource-allocation graph. GSK cannot currently exactly represent this type of graph because an assignment edge is drawn from a dot within a resource node to a process node as shown in Figure 9. However, the student was still able to use GSK to create modified resource allocation graphs and use them to detect deadlock and other resource contention problems and determine how they might be resolved. For a quiz, he was given a textual description of the resource-allocation graph in Figure 9. He was able to render it using GSK as shown in Figure 10

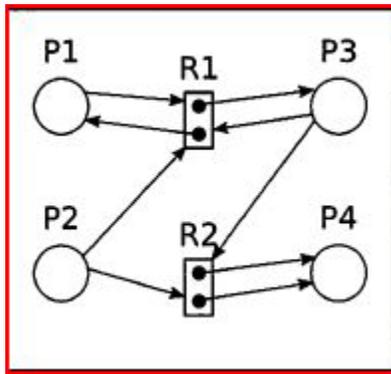


Figure 9. Resource-allocation Graph

and solve the related problems using only 5 minutes more than his sighted peers, who were provided with the node-link diagram version of the graph.

5. FUTURE WORK

We are very encouraged based on the successful use of GSK in the aforementioned courses. The sighted Automata Theory teaching assistant found creating graphs with GSK to be quite simple and straightforward and expressed interest in using it to create homework solution sets. Thus, GSK appears to have universal appeal.

We plan to have a class of sighted students beta-test GSK and afterwards carry out controlled user studies with both blind and sighted participants. The user studies will help determine whether the interface and paradigm are intuitive as well as how close GSK comes to providing blind and sighted people with computationally equivalent access to graphs.

We will continue to improve GSK, incorporating feedback from the user studies as well as our own ideas, in hopes of providing blind people with greater access to graphs in a universally accessible and appealing way.

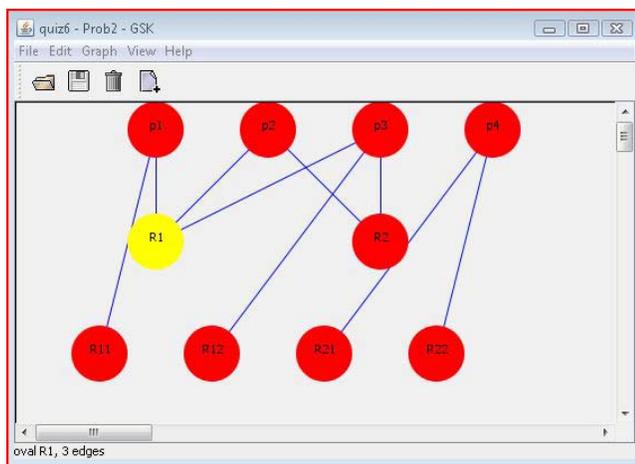


Figure 10. Resource-allocation Graph

6. ACKNOWLEDGMENTS

We would like to thank Dr. Richard Ladner for the AccessComputing mini-grant that supported this work via NSF Award #CNS-0837508.

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